

# Reactive Programs

A thick, hand-drawn style orange line underlining the text.

# Example 1: vending machine

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Takes 3 coins to get a coke

If you put 3 coins, you can select a drink  
(as long as you don't cancel in the middle)

After you select your drink you get your  
drink

If you press cancel, you get your money back



# Example 2: ignition button

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Engine starts and stops with button push

If engine is off, it stays off until I push

- If I never push it stays off forever

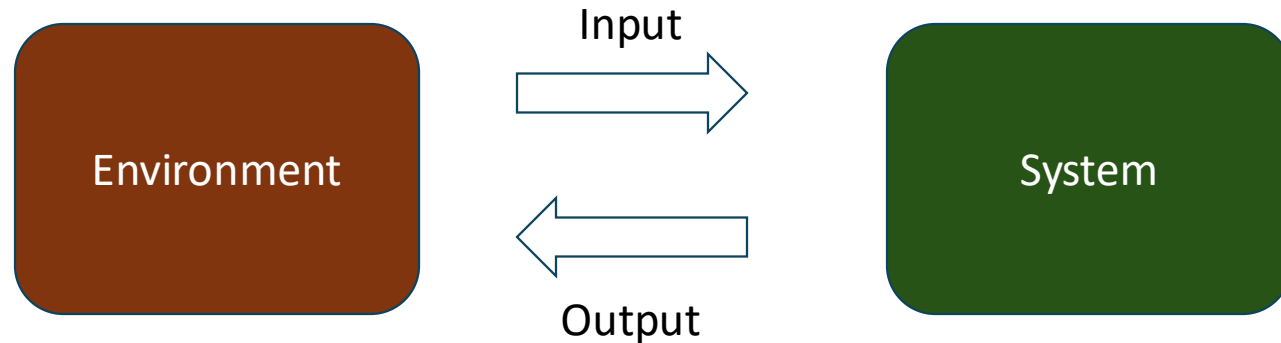
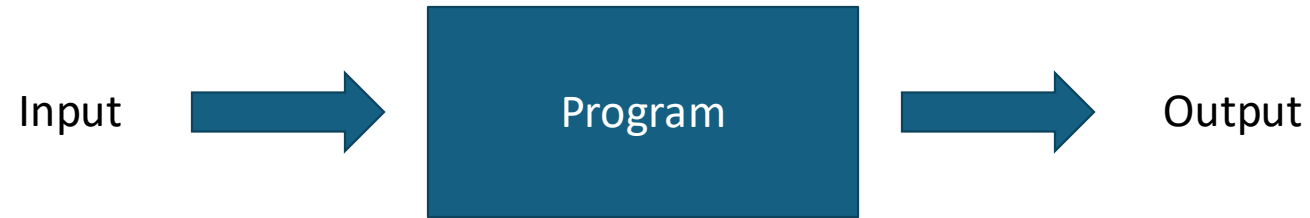
If engine is on, it stays on until I push

- If I never push it stays on forever



# What is a reactive program?

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# Reactive systems as algorithms

How do we describe reactive systems?

- Finite state model

How do we specify their behavior?

- Monadic Second Order (MSO) logic, Linear Temporal Logic (LTL)

How to verify?

- Satisfiability of MSO  $\Rightarrow$  Emptiness of Automata

How to design?

- Reactive system as a game
- Program implemented as a strategies (Realizability vs. Synthesis)

# Finite state models

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A reactive system can be naturally described as a *finite state transducer*

- There are finitely many controls/states
- Input is from a finite set  $I$
- Action is from a finite set  $A$
- “coin-coin-coin-drink-coin-coin-cancel-return2coins-...”

The behaviors are commonly defined as a *finite state automaton*

- Pair interleaved input-action
- Alphabet:  $(I \cup \{\epsilon\}) \times (A \cup \{\epsilon\})$
- “(coin,  $\epsilon$ )-(coin,  $\epsilon$ )-(coin, drink)-(coin,  $\epsilon$ )-(coin,  $\epsilon$ )-(cancel, return2coins)-...”

# DFA

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A *deterministic finite automaton* is  $A = (\Sigma, Q, q_0, \delta, F)$  where

- $\Sigma$  is the alphabet
- $Q$  is a finite set of states
- $q_0 \in Q$  is the initial state
- $\delta: Q \times \Sigma \rightarrow Q$  is a deterministic transition table
- $F \subseteq Q$  is a set of accepting states

A word is accepted by  $A$  if running  $A$  over the word stops at an accepting state

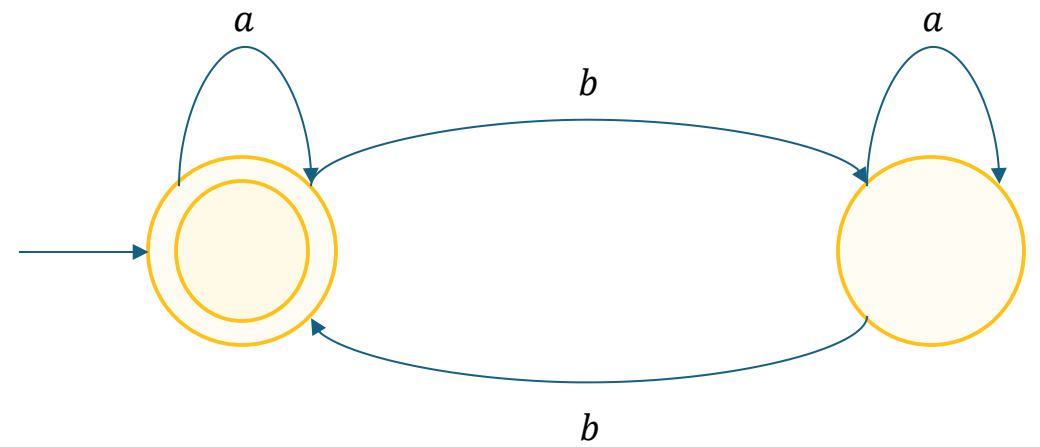
$L(A)$ : the language of  $A$  (the set of words accepted by  $A$ )

# Example

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$$\Sigma = \{a, b\}$$

Design a DFA  $A$  such that  $L(A)$  is the set of all words containing even number of  $b$ 's:





# NFA

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A *nondeterministic finite automaton* is  $A = (\Sigma, Q, q_0, \delta, F)$  where

- $\Sigma$  is the alphabet
- $Q$  is a set of states
- $q_0 \in Q$  is the initial state
- $\delta \subseteq Q \times \Sigma \cup \{\epsilon\} \times Q$  is a nondeterministic transition table
- $F \subseteq Q$  is a set of accepting states

A word is accepted by  $A$  if a lucky run over the word stops at an accepting state

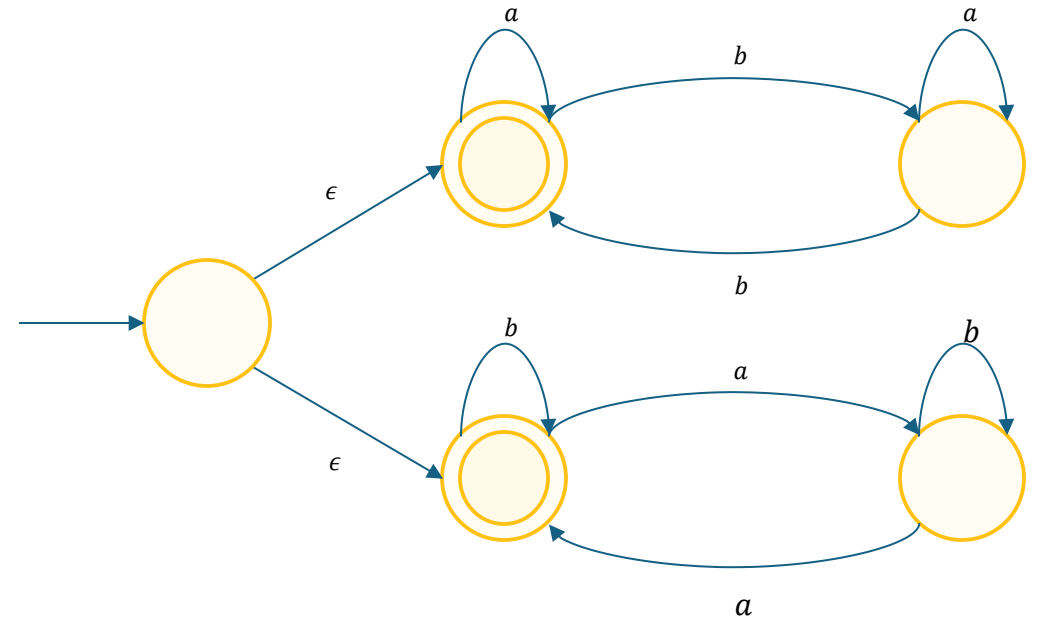
## Theorems:

- NFA = DFA = Regular expressions
- NFA/DFA is closed under complementation, union, intersection
- Emptiness is decidable

# Example

$$\Sigma = \{a, b\}$$

Design a DFA  $A$  such that  $L(A)$  is the set of all words containing even number of  $a$ 's or even number of  $b$ 's:



# Regular expression

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$R$  is a regular expression if  $R$  is

- $a$  for some  $a$  in the alphabet  $\Sigma$
- $\epsilon$
- $\emptyset$
- $(R_1 \cup R_2)$  where  $R_1$  and  $R_2$  are regular expressions
- $(R_1 \circ R_2)$  where  $R_1$  and  $R_2$  are regular expressions
- $(R_1^*)$  where  $R_1$  is a regular expression

Theorems:

- Regular expressions  $\Rightarrow$  NFA
- DFA  $\Rightarrow$  Regular expressions

# Monadic Second Order Logic

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# Second-Order Logic

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Second-Order (SO) logic extends FOL with second-order variables

- E.g.,  $R^1$  (a set variable),  $R^2$  (a relation variable),  $F^1$  (a unary-function variable),  $F^2$  (a binary-function variable) ...
- $\exists F^2 \forall x, y (F^2(x, y) = F^2(y, x) \wedge \dots)$
- Sound and complete proof system does not exist

Monadic Second-Order (MSO) logic allows set variables only

- E.g.,  $\exists S (\dots \exists x (x \in S \wedge \dots))$

## Example

the length of the word is even?

$$\exists R \exists G \left( \begin{array}{l} \forall x (\neg R(x) \vee \neg G(x)) \\ \wedge R(0) \\ \wedge \forall x \forall y (S(x, y) \wedge R(x) \rightarrow G(y)) \\ \wedge \forall x \forall y (S(x, y) \wedge G(x) \rightarrow R(y)) \\ \wedge \forall y (\text{last}(y) \rightarrow G(y)) \end{array} \right)$$



# Logic vs. Automata

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**Theorem (Buchi-Elgot-Trakhtenbrot 1960)** : A language  $L \in \Sigma^+$  is regular iff.  $L$  is MSO-definable.

- $\Rightarrow$ : Given a NFA  $A$ , Construct an MSO sentence over finite words that precisely describes  $L(A)$
- $\Leftarrow$ : Given an MSO sentence  $\varphi$ , construct a NFA that accepts precisely the language defined by  $\varphi$

**Corollary:** The satisfiability of MSO over finite words is decidable.

# NFA to MSO

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$A = (\Sigma, Q, q_0, \delta, F)$ ,  $Q = \{q_0, \dots, q_k\}$ , the accepting sequence is in  $Q^+$ .

$$\varphi_A = \exists X_0 X_1, \dots X_k:$$

$$\wedge \wedge_{i \neq j} \forall y \neg (X_i(y) \wedge X_j(y))$$

$$\wedge X_0(0)$$

$$\wedge \forall y, z \left( s(y, z) \Rightarrow \bigvee_{(i,a,j) \in \delta} \left( X_i(y) \wedge Q_a(y) \wedge X_j(z) \right) \right)$$

$$\wedge \forall y (last(y) \Rightarrow \bigvee_{j \in F} X_j(y))$$



# MSO to NFA

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$x \in X \mid x = y \mid s(x, y) \mid Q_a(x) \mid \exists x \varphi(x) \mid \exists X \varphi(X) \mid \varphi \vee \varphi \mid \neg \varphi$

Remove first-order variables:

$Sing(X) \mid X \subseteq Y \mid Suc(X, Y) \mid X \subseteq Q_a \mid \exists X \varphi(X) \mid \varphi \vee \varphi \mid \neg \varphi$

Inductively convert:

- $\varphi \rightarrow A(\varphi)$  (DFA over  $\Sigma$ )
- $\varphi(X_1, \dots, X_n) \rightarrow A(\varphi)$  (DFA over  $\Sigma \times \{0,1\}^n$ )

# Büchi Automata

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# Infinite words

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- DFA/NFA accept words of finite length.
- How about infinite words?
  - E.g., “ababababab...”
- An *infinite word* is a map  $\alpha: \mathbb{N} \rightarrow \Sigma$ .
  - E.g.,  $\alpha(i) = \begin{cases} a & \text{if } i \text{ is even} \\ b & \text{otherwise} \end{cases}$
- The set of all infinite words is denoted as  $\Sigma^\omega$ .

# Büchi automata

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How can an automaton accept an infinite word?

- Büchi automata (named after Purdue's Julius Richard Büchi)
- “an accepting state is hit infinitely many times”

# Büchi automata

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A *Büchi Automaton* (BA) is  $A = (\Sigma, Q, q_0, \delta, F)$  where

- $\Sigma$  is the alphabet
- $Q$  is a finite set of states
- $q_0 \in Q$  is the initial state
- $\delta \subseteq Q \times \Sigma \times Q$  is a nondeterministic transition table
- $F \subseteq Q$  is a set of accepting states

A run of  $A$  on an infinite word  $\alpha$  is a map  $r: \mathbb{N} \rightarrow Q$  such that  $r(0) = q_0$ , and for any  $i \in \mathbb{N}$ ,  $(r(i), \alpha(i), r(i+1)) \in \delta$

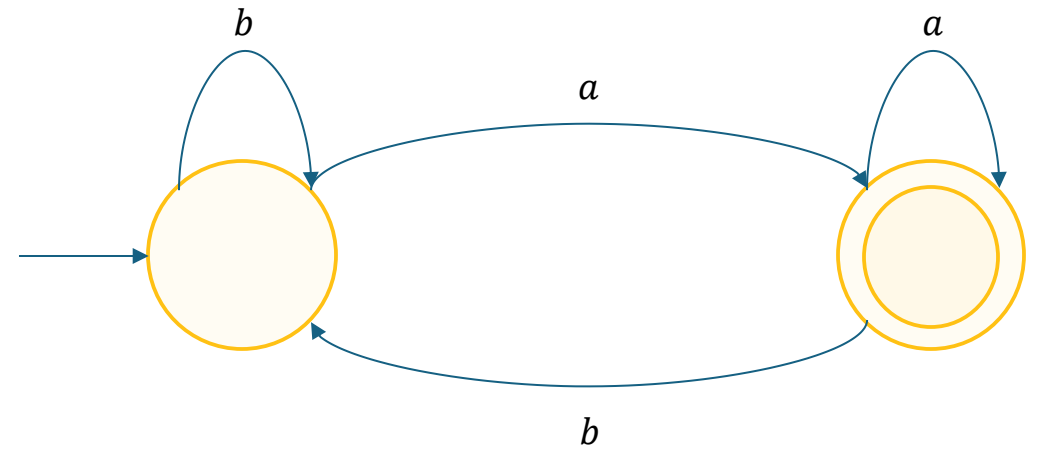
$r$  is accepting if  $r(i) \in F$  for infinitely many  $i \in \mathbb{N}$

A word  $\alpha$  is accepted by  $A$  if there is some accepting run of  $A$  on  $\alpha$

# Example

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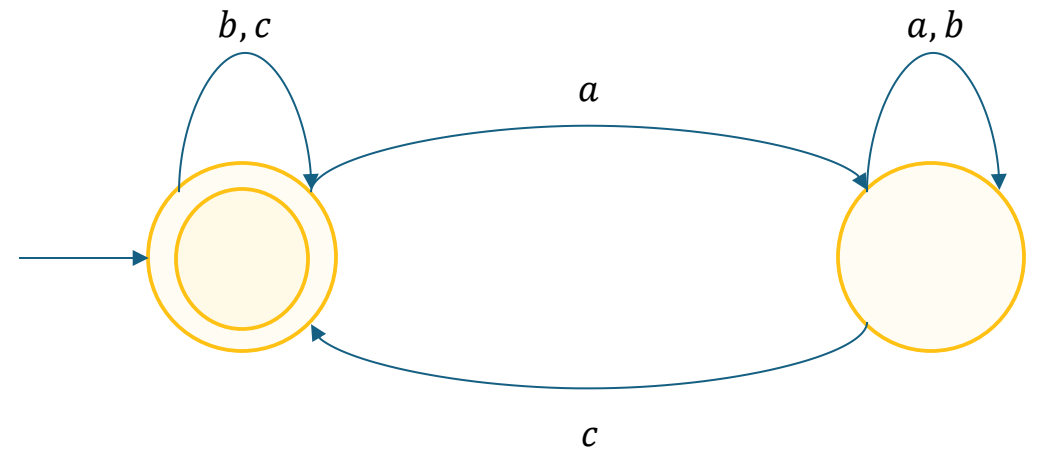
$L = \{ \alpha \in \{a, b\}^\omega \mid \alpha \text{ has infinitely many } a\text{'s} \}$



# Example

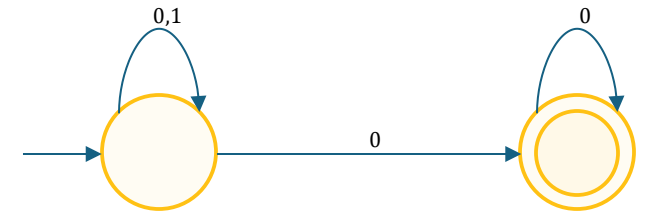
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“Every ‘a’ must be followed eventually by a ‘c’.”



# Properties of BA

- BA is closed under
  - Union
  - Intersection
  - Complementation ( $2^{n \cdot \lg n}$  blow-up )
  - Projection
- BA is not determinizable!
  - E.g., infinite words over  $\{0,1\}^\omega$  that contain finitely many 1's
- Emptiness of BA is decidable (NLOGSPACE-complete)





# Decision Procedure for MSO

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- Implementation:
  - Mona (<https://www.brics.dk/mona/>)
- How is the complexity?
  - Not elementary:  $2^{2^{\dots^n}}$

# Linear Temporal Logic

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# Logic vs. Automata, round 2

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**Theorem (Büchi 1960):** A language  $L \in \Sigma^\omega$  is regular iff.  $L$  is MSO-definable.

**Corollary:** The satisfiability of MSO over infinite words is decidable.

# “Algorithm not very efficient”

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Implementation:

- Mona (<https://www.brics.dk/mona/>)

How is the complexity?

- Not elementary:  $2^{2^{\dots^n}}$

# Linear Temporal Logic (Pnuerli 1977)

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Syntax:

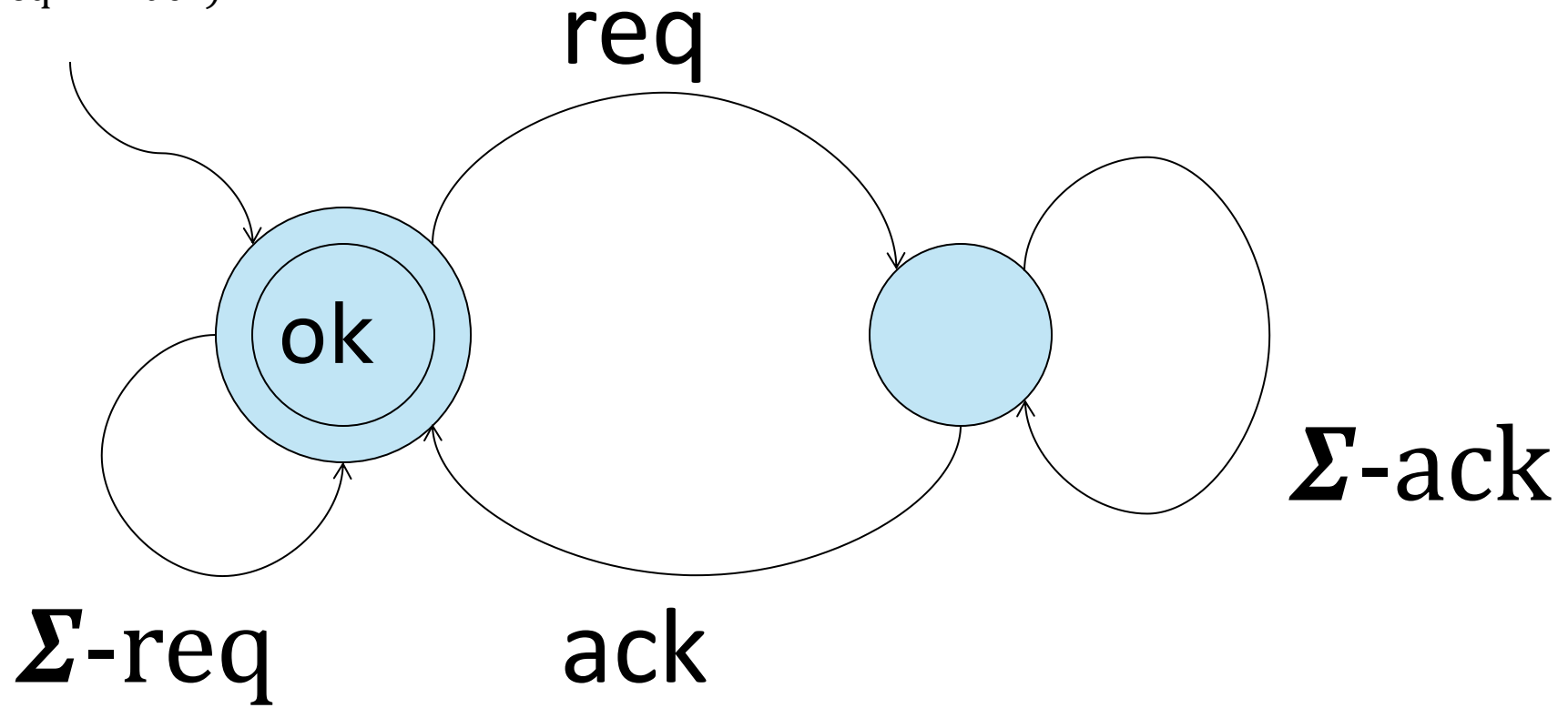
$LTL :: - \text{true} \mid p \mid X \alpha \mid F \alpha \mid G \alpha \mid \alpha U \beta \mid \alpha \vee \beta \mid \neg \alpha$

*“next” “eventually” “always” “until”*

Semantics: interpreted over infinite traces

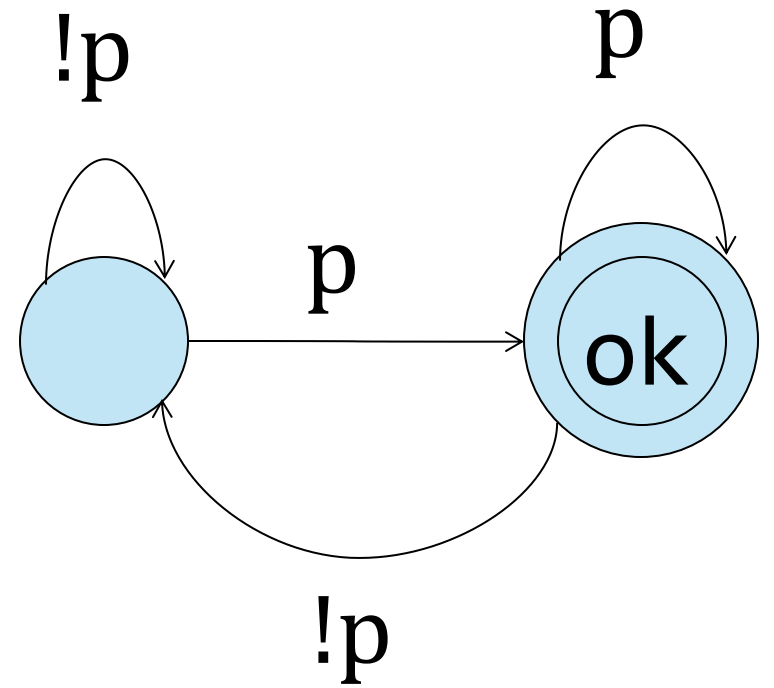
# Example

$G (\text{req} \rightarrow F \text{ack})$



# Example

$G F p$



# LTL to FO

For infinite words (or  $(\mathbb{N}, <)$ ):

- $\text{LTL} = \text{FO} = \text{star-free regular language} < \text{MSO} = \text{BA}$   
= Regular language

$\varphi_{\text{LTL}}$  to  $\varphi_{\text{FO}}(x)$  by structural induction:

- $p \Rightarrow \bigvee_{p \in Y} Q_Y(x)$
- $X \varphi \Rightarrow \exists y (s(x, y) \wedge \varphi_{\text{FO}}(y))$
- $F \varphi \Rightarrow \exists y (x \leq y \wedge \varphi_{\text{FO}}(y))$
- $\varphi U \psi \Rightarrow \exists y \left( x \leq y \wedge \psi_{\text{FO}}(y) \wedge \forall z (x \leq z < y \rightarrow \varphi_{\text{FO}}(z)) \right)$
- $\varphi_1 \vee \varphi_2 \Rightarrow \varphi_{1_{\text{FO}}}(x) \vee \varphi_{2_{\text{FO}}}(x)$
- $\neg \varphi \Rightarrow \neg \varphi_{\text{FO}}(x)$



# LTL to BA

## Why LTL?

- More efficient algorithm!

## A maximal-model-based algorithm (Wolper-Vardi-Sistla 1983)

- Intuition: compute the maximal set of satisfied subformulae
- E.g.,  $\varphi : p \ U (\neg p \wedge q)$
- With input:  $p, \ pq, \ p, \ q, \ p, \ \emptyset, \ q, \ \dots$

# Closures

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How to define the subformulae?

Let  $\varphi$  be LTL, then  $CL(\varphi)$  is the smallest set satisfying:

- $\varphi \in CL(\varphi)$
- If  $\neg\psi \in CL(\varphi)$ , then  $\psi \in CL(\varphi)$
- If  $\varphi_1 \vee \varphi_2 \in CL(\varphi)$ , then  $\varphi_1, \varphi_2 \in CL(\varphi)$
- If  $X \psi \in CL(\varphi)$ , then  $\psi \in CL(\varphi)$
- If  $\varphi_1 U \varphi_2 \in CL(\varphi)$ , then  $\varphi_1, \varphi_2, X \varphi_1 U \varphi_2 \in CL(\varphi)$



# Atoms

$A \subseteq CL(\varphi)$  is an atom (maximally consistent subset) if

- $\forall \neg\varphi' \in CL(\varphi), \varphi' \in A \text{ iff } \neg\varphi' \notin A$
- $\forall \varphi_1 \vee \varphi_2 \in CL(\varphi), \varphi_1 \vee \varphi_2 \in A \text{ iff } \varphi_1 \in A \text{ or } \varphi_2 \in A$
- $\forall \varphi_1 U \varphi_2 \in CL(\varphi), \varphi_1 U \varphi_2 \in A \text{ iff } \varphi_2 \in A \text{ or } (\varphi_1 \in A \text{ and } X \varphi_1 U \varphi_2 \in A)$

# LTL to BA

States: set of atoms of  $\varphi$

Transitions:  $(A_1, X, A_2) \in \delta$  if and only if

- $A_1 \cap Voc(\varphi) = X$
- $\forall X \varphi_1 \in CL(\varphi), X \varphi_1 \in A_1 \text{ iff } \varphi_1 \in A_2$

Initial states:  $\{A \mid \varphi \in A\}$



# LTL to BA

## When to accept?

- For every  $\varphi_1 U \varphi_2$  in the atom,  $\varphi_2$  has to eventually occur!
- A “good” state either does not have  $\varphi_1 U \varphi_2$  or has  $\varphi_2$
- Good states must be infinitely many:
- $F_i = \{A \in Atoms(\varphi) \mid \varphi_1 U \varphi_2 \notin A \text{ or } \varphi_2 \in A\}$
- Accepting states:  $F_i$  for every  $\varphi_1 U \varphi_2$

Complexity:  $2^{O(|\varphi|)}$

# Model Checking

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**Model Checking Problem:** Given a finite transition system  $TS$  and an LTL formula  $\varphi$ , does every sequence  $\alpha$  generated by  $TS$  satisfies  $\varphi$ ?

Check:  $L(A_{TS} \wedge A_{\neg\varphi}) = \emptyset$  ?

Complexity:  $2^{O(|\varphi|)} \cdot |TS|$

Implementation: NuSMV

# Reactive Synthesis

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# Cinderella Game

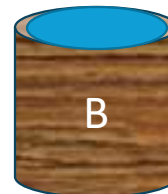
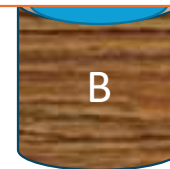
## Cinderella

- Can empty two **adjacent** buckets
- If she can keep stepmother from winning, she wins

## Stepmom

- Splits her water among all buckets
- If any overflows she wins

What is the B for which the advantage shifts from stepmother to Cinderella?





# Stepmother's Perspective

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She is trying to satisfy *F overflow*

What is the largest  $B^*$  such that if  $B < B^*$  she wins?

$\exists \text{Strategy}, \forall \text{cind}, B \ B < B^* \Rightarrow \text{win}(\text{Strategy}, \text{cind})$



# Cinderella's perspective

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She is trying to satisfy  $G \neg \text{overflow}$

If  $B < 1$  this is impossible

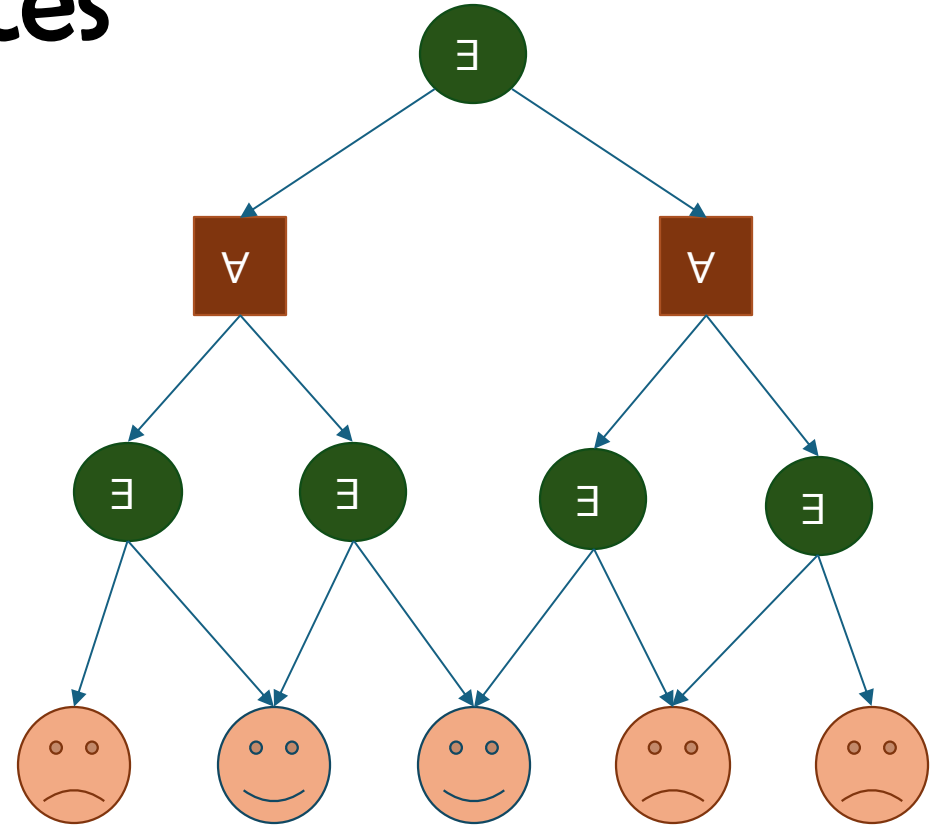
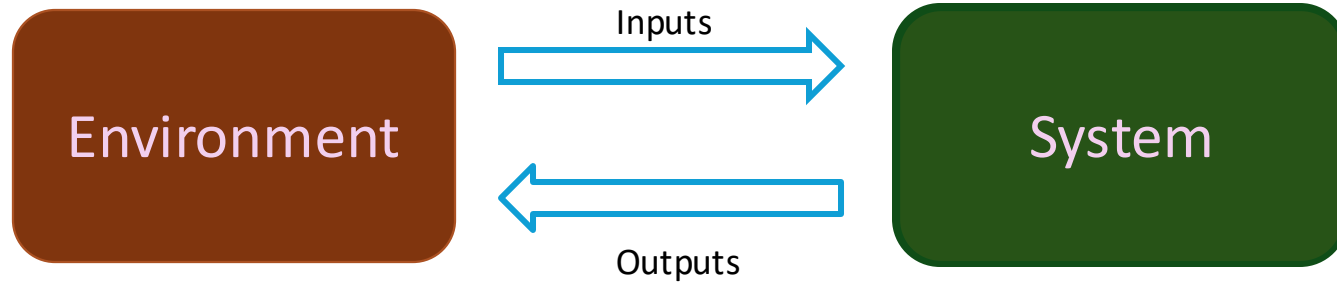
What is the smallest  $B^*$  such that if  $B > B^*$  she is safe?

$\exists \text{Strategy}, \forall \text{mom}, B \ B > B^* \Rightarrow$   
 $\text{win}(\text{Strategy}, \text{mom})$

$B^* = 2$



# System evolution a tree of choices



**Environment:** choose an input from a set  $I$

**System:** choose an output from a set  $O$

**Strategy:** a function  $f: I^* \rightarrow O$

**Winning Condition:** An MSO formula on  $I \cup O$

**Winning Strategy:** all plays satisfy the winning condition

# Realizability

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**Church's Problem (1957):** the existence of winning strategy for specification expressed in MSO.

- Synthesis: obtaining such winning strategy

**MSO Realizability (Büchi-Landweber 1969):** the MSO Realizability problem is decidable.

- If a winning strategy exists, then a finite-state strategy exists.
- Realizability algorithm produces finite-state strategies.

# Rabin's Realizability Algorithm (1972)

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Rabin Tree Automata on infinite  $k$ -ary trees:  $A = (\Sigma, Q, q_0, \delta, F)$  where

- $\Sigma$  is the alphabet
- $Q$  is a finite set of states
- $Q_0 \subseteq Q$  is the initial state set
- $\delta: Q \times \Sigma \rightarrow 2^{Q^k}$  is a nondeterministic transition table
- $\alpha \subseteq 2^{2^Q \times 2^Q}$  is a set of accepting conditions

Acceptance Condition:

- Let  $\alpha = \{(G_1, B_1), \dots, (G_l, B_l)\}$ ,  $G_i, B_i \subseteq Q$
- Along every branch, for some  $i$ ,  $G_i$  is visited infinitely often, and  $B_i$  is visited finitely often

# Rabin's Realizability Algorithm (1972)

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## Emptiness of Tree Automata

- PTIME on finite trees (Doner 1965)
- NP-complete on infinite trees (Emerson-Jutla 1991)

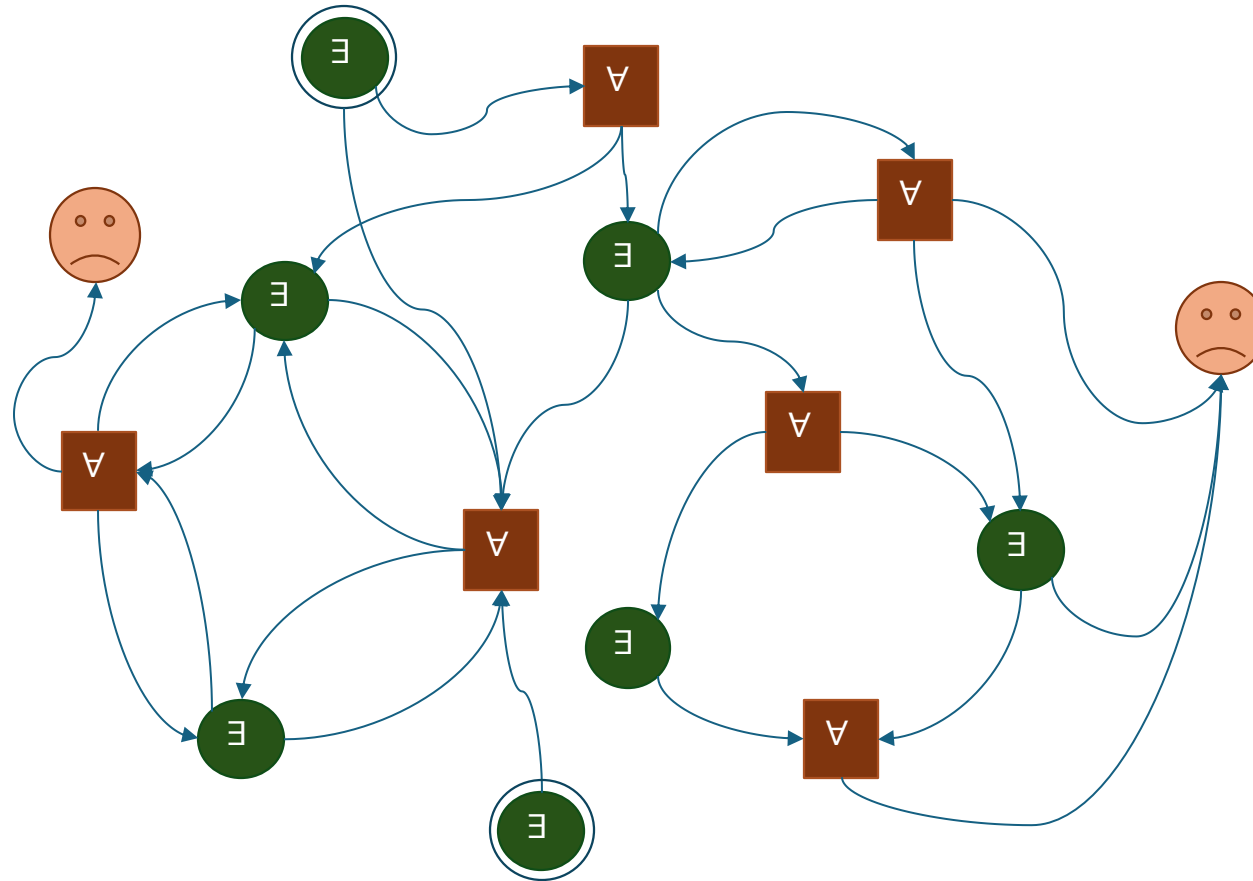
## Real( $\varphi$ ):

- A strategy can be represented as labels on the infinite game tree
- Construct a Rabin tree automaton  $A_\varphi$  that accepts a labeled tree iff the labels represent a strategy, and the strategy is winning wrt to the condition  $\varphi$
- Check the emptiness of  $A_\varphi$ ; if nonempty, extra a strategy from the witness

## Complexity:

- non-elementary (the construction of  $A_\varphi$ )
- 2EXPTIME-complete for LTL spec (Rosner 1990)

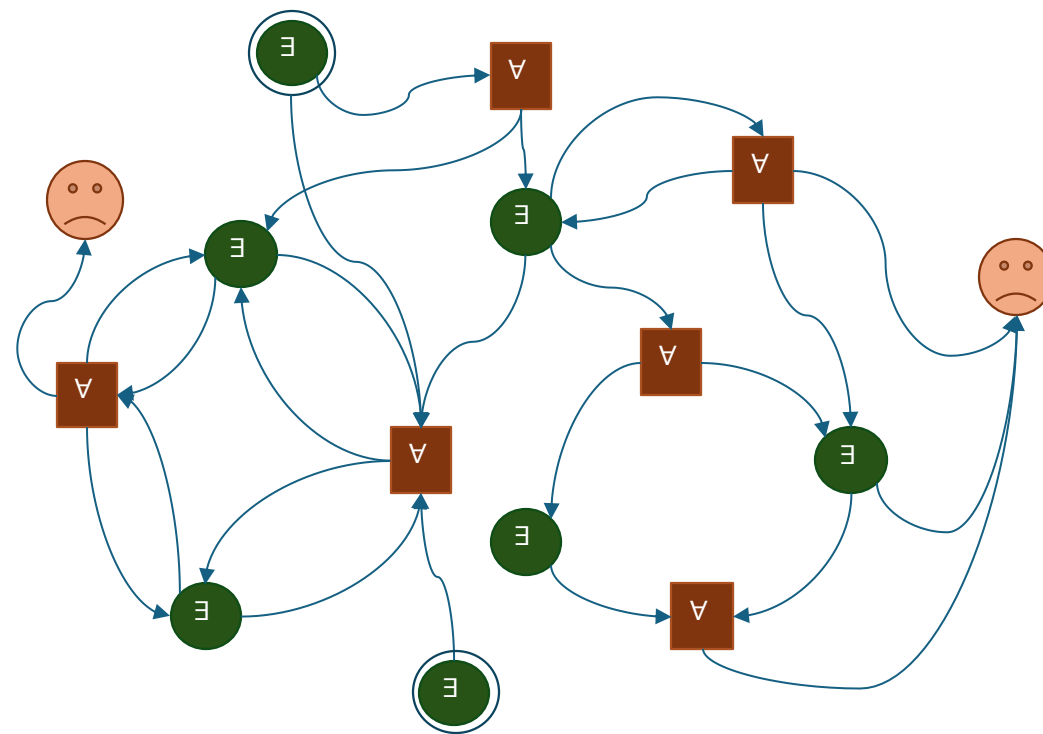
# System/Environment as a graph



# Two-person games

Winning condition:

- In general, LTL formulas
- Expensive! (double exponential)
- Reachability games
- Safety games
- ??





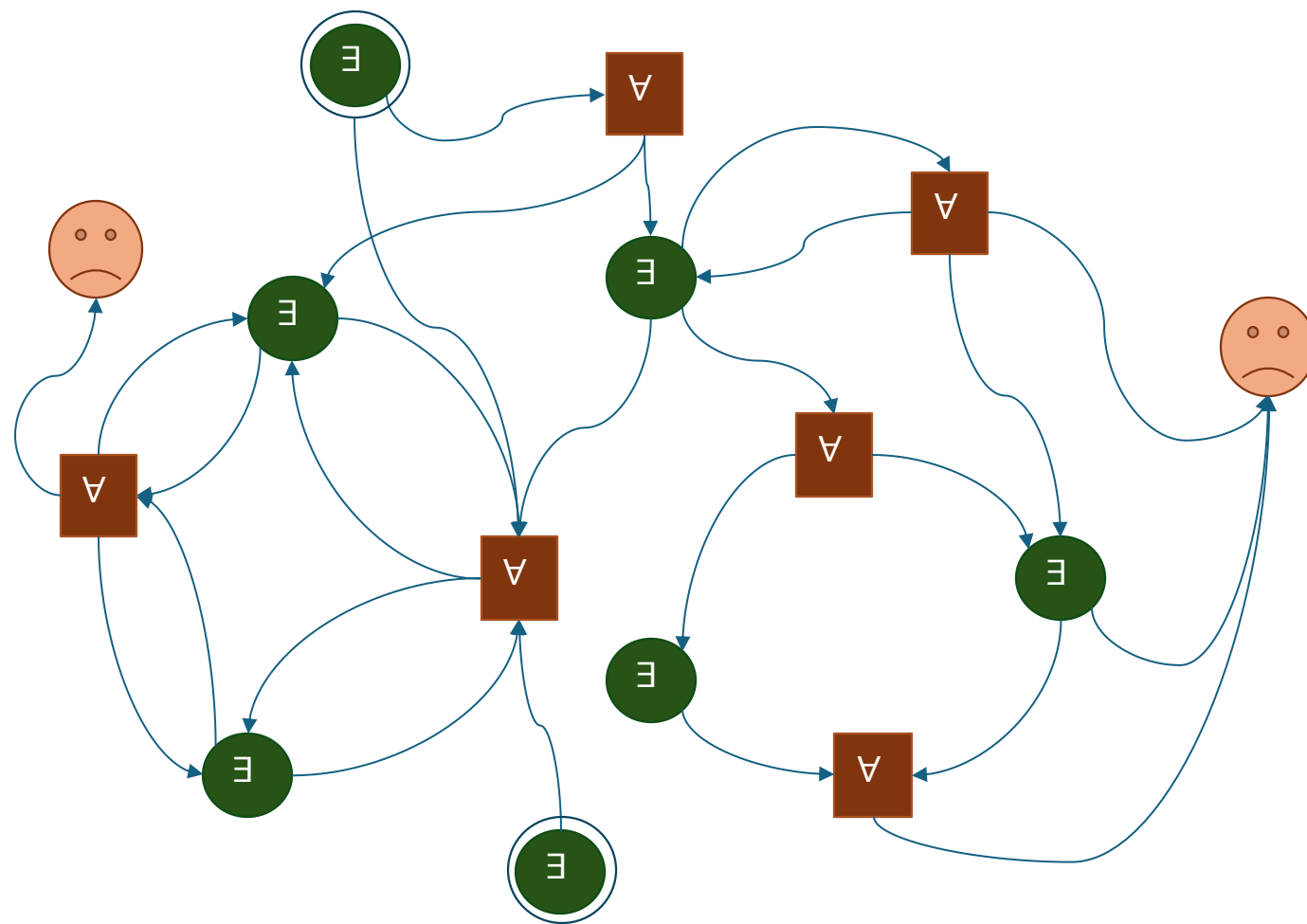
# Specialized games

LTL provides a general language for specifications

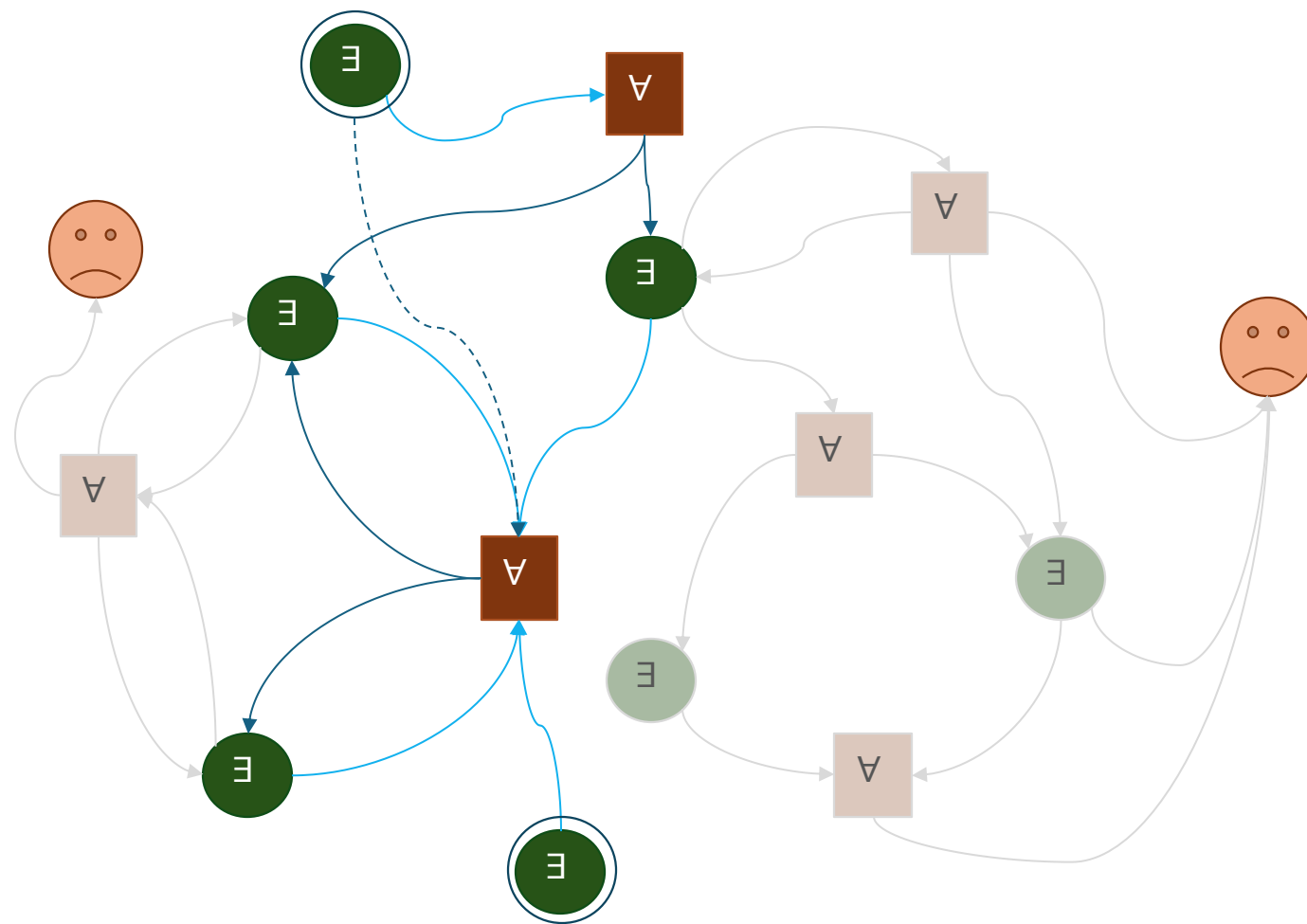
- Safety Games ( $G\ p$ )
  - System “wins” if it can stay away from the bad states  $\neg p$
- Reachability Games ( $F\ p$ )
  - System “wins” if it can reach a good state that satisfies  $p$
  - $F\ p$  are often referred to as *liveness properties*



# Solving reachability games



# Solving reachability games





# Reachability games enjoy memoryless strategies

At every  $\exists$  state, the decision of what transition to make depends only on the current state

- easy to translate into code

## Finite vs. Infinite Games

- Chess & Go
- Banach–Mazur game
- For finite games, one of the players has a winning strategy

# Synthesis of AMBA AHB from Formal Spec

AMBA: Advanced Microcontroller  
Bus Architecture

AMBA AHB: a high-performance  
system backbone bus

- Formal Spec written in LTL
- Circuit automatically synthesized!
- AHB Slave synthesized in 21.5 second,
- (has 214 gates with area 429 square units)

